

Abstract

A device for carrying and fastening a robot (4), in particular a delta robot, is designed in a gallows shape. It has a foot (1), a column (2) adjoining the foot (1), and at least one cantilever arm (3), fastened to this column (2), for fastening the robot (4). The cantilever arm (3) in this case is fastened to the column (2) in a fixed position. The device consists at least partly of a composite material, in particular a cast mineral. This device for carrying and fastening a robot is extremely space-saving and nonetheless has good vibration-damping properties.

(Fig. 1)